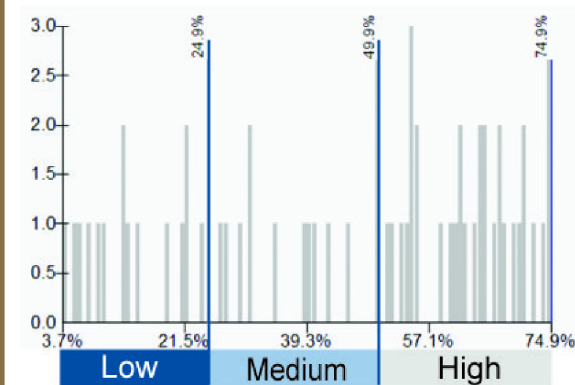


This map shows accessibility to jobs within a half hour bike ride during the morning commute. Analysis for this map assumes bikes travel at 10 mph and routes include off-road pathways, roads with lower auto volumes, and lower slopes. All jobs are included except self-employment.

This map is based on results from the regional travel demand model of the Central Lane Metropolitan Planning Organization, and reflects conditions around January 2011. For this map, data was analyzed at the transportation analysis zone level then aggregated to the tract level. Information for the tracts that fall outside the Metropolitan Planning Organization area may be limited to transportation analysis zones within distance of the area boundary, and do not include data for the entire tract.

For this map, the data was classified with defined breaks of 0-24.9%, 25-49.9%, and 50% and over. This is the same classification as the other job accessibility maps for comparison purposes. A histogram is also included to show how the data distributed across these three categories.



Map date: 12/18/13 Map data: Lane Council of Governments.
 Caution: This map is based on imprecise source data, subject to change, and for general reference only. The work that provided the basis for this map was supported by funding under an award with the U.S. Department of Housing and Urban Development. The substance and findings of the work are dedicated to the public. The author and publisher are solely responsible for the accuracy of the statements and interpretations contained in this publication. Such interpretations do not necessarily reflect the views of the Government.

- Census 2010 Tracts
- Metropolitan Planning Organization Area boundary
- Urban Growth Boundaries

Percentage of Jobs Accessible within a 30 Minute Bike Ride

- Low: 3.7% - 24.9%
- Medium: 25% - 49.9%
- High: 50% - 74.9%

The chart to the right shows the number of tracts in the Metropolitan Planning Organization Area that have low, medium, and high percentages.

